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Numerical Methods for Partial Differential Equations

Numerical solution of Advection Diffusion Reaction problems

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`help fem_1d_adsolver`

```
fem_1d_adsolver: solve -mu u'' + bu' + sigma u = f in Omega  
with Dirichlet and/or Neumann boundary conditions  
by either P1-fem or P2-fem on a uniform grid.
```

```
[nodes,uh]=fem_1d_adsolver(geom,problem_data,p,Ne)  
[nodes,uh]=fem_1d_adsolver(geom,problem_data,p,Ne,degree)
```

Input: geom: struct with fields:

.....

Output: nodes = column array with the nodes of the mesh
uh = column array of the numerical solution



Problem 1 (1d Advection Diffusion (AD))

Solve the AD problem

$$\begin{cases} -\mu u'' + bu' = 0 & \text{in } \Omega = (0, 1) \\ u(0) = 0, u(1) = 1. \end{cases}$$

(with $\mu = 1, 0.1, 0.02$ and $b = 1$) by FEM- \mathbb{P}_1 and FEM- \mathbb{P}_2 . Take $Ne = 10, 20, 30, 40, 80, 160, 320$.

1. Compute the Péclet number $\mathbb{P}e = \frac{b}{\mu} \frac{h}{2}$ and verify that the numerical solution does not show oscillations when $\mathbb{P}e < 1$.
2. The exact solution of the equation is

$$u(x) = \frac{e^{xb/\mu} - 1}{e^{b/\mu} - 1}.$$

Verify that the error $\|u - u_h\|_{H^1(\Omega)}$ converges linearly to zero for \mathbb{P}_1 -fem and quadratically for \mathbb{P}_2 -fem, provided that $\mathbb{P}e < 1$.



Problem 2 (1d Advection Diffusion (AD))

Solve the problem

$$\begin{cases} -\mu u'' + bu' = 0 & \text{in } \Omega = (0, 1) \\ u(0) = 0, u(1) = 1. \end{cases}$$

(with $\mu = 0.02$ and $b = 1$) by FEM- \mathbb{P}_1 and FEM- \mathbb{P}_2 , by using the **artificial diffusion** method (i.e., replace μ with $\mu_h = \mu(1 + \mathbb{P}e)$)
Take $Ne = 10, 20, 30, 40, 80, 160, 320$.

1. Verify that spurious oscillations are missing for any value of h , even when $\mathbb{P}e > 1$.
2. The exact solution is

$$u(x) = \frac{e^{xb/\mu} - 1}{e^{b/\mu} - 1},$$

verify that the error $\|u - u_h\|_{H^1(\Omega)}$ converges linearly to zero both for \mathbb{P}_1 -fem and \mathbb{P}_2 -fem



Problem 3

Solve the problem

$$\begin{cases} -\mu\Delta u + \mathbf{b} \cdot \nabla u + \sigma u = f & \text{in } \Omega = (0, 1)^2 \\ u = g_D & \text{on } \partial\Omega \end{cases}$$

where $\mu = 10^{-3}$, $\mathbf{b} = [1, 1]^T$, $\sigma = 0$, $f = 1$, $g_D = 0$.

1. Set $\delta = 0$ (classical Galerkin), and compute the numerical solution with $h = 1/20$ and $h = 1/80$.
2. set $\delta = 1$ and compute the numerical solution with $h = 1/20$ and $h = 1/80$.
3. Repeat the work with $\mu = 10^{-5}$ instead of $\mu = 10^{-3}$.



Advection Diffusion Reaction, $d = 2$

```
% FEM_2D_AD Computes the GaLS-FEM-P1 approximation of  
% -mu Delta u+ b . nabla u +sigma u=f in Omega (2D domain)  
% u=g_D Dirichlet conditions on the boundary.
```

```
% GaLS=Galerkin-Least-Squares stabilization
```

```
[u,FEM]=fem_2d_ad(model ,problem_data ,parameters)
```

Input:

```
model = model object generated by MATLAB (it must contain  
field model.Mesh)
```

```
problem_data = struct with fields:
```

```
    .mu = coefficient (constant) of 2nd order term
```

```
    .b = velocity field (constant) of 1st order term
```

```
    .....
```

Output:

```
u = numerical solution
```

```
FEM = struct with fields:
```

```
    .Kc: % matrix A0, (i,j) non-dirichlet
```

```
    .Fc: % rhs f0, (i) non-dirichlet
```

```
    .....
```



Galerkin Least Squares GaLS stabilization

GaLS formulation: find $u_h \in V_h$:

$$a(u_h, v_h) + \sum_k \int_{T_k} L u_h \tau_k L v_h = F(v_h) + \sum_k \int_{T_k} f \tau_k L v_h \quad \forall v_h \in V_h$$

with $\tau_k = \delta \frac{h_k}{|\mathbf{b}|}$ **stabilization parameter** $\delta > 0$.

1. Because $Lu = f$, (u is the exact solution), we have

$$\sum_k \int_{T_k} L u \tau_k L v_h = \sum_k \int_{T_k} f \tau_k L v_h \quad \forall v_h \in V_h, \text{ this}$$

method is strongly consistent, meaning that the exact solution satisfies the discrete equation exactly.

2. For each $v_h \in X_h$ (the space \mathbb{P}_1), because μ is constant, it holds $-\nabla \cdot (\mu \nabla v_h) = 0$, thus

$$\int_{T_k} L u_h \tau_k L v_h = \int_{T_k} (\mathbf{b} \cdot \nabla u_h + \sigma u_h) \tau_k (\mathbf{b} \cdot \nabla v_h + \sigma v_h).$$

3. If $\delta = 0$, GaLS reduces to classical Galerkin method.



Solution of Problem 3

```
model=createpde; % build the model
% build the geometry
Q1=[3,4, 0,1,1,0, 0,0,1,1]';
gd=[Q1];
ns=(char('Q1'))';
sf='Q1';
g=decsg(gd,sf,ns);
geometryFromEdges(model,g);
% build the mesh
generateMesh(model,'Hmax',1/20,...
              'GeometricOrder','linear');
% set problem_data and parameters
% call fem_2d_ad
[u]=fem_2d_ad(model,problem_data,parameters);
% plot the solution
pdeplot(model,'XYData',u,'ZData',u,...
         'Contour','on','Mesh','on')
```



Description of the output struct FEM

Let us consider the problem

$$\begin{cases} Lu = -\mu \Delta u + \mathbf{b} \cdot \nabla u + \sigma u = f & \text{in } \Omega \\ u = g_D & \text{on } \partial\Omega \end{cases}$$

with constant $\mu > 0$, constant \mathbf{b} , constant $\sigma \geq 0$.

The weak form reads: **find** $u = u_0 + Rg_D$, where:

– u_0 is the **homogeneous part** of u

$$u_0 \in H_0^1(\Omega) : \quad a(u_0, v) = F(v) \quad \forall v \in H_0^1(\Omega)$$

with

$$a(u, v) = \int_{\Omega} \mu \nabla u \cdot \nabla v + \int_{\Omega} (\mathbf{b} \cdot \nabla u) v + \int_{\Omega} \sigma u v, \quad F(v) = \int_{\Omega} f v$$

– while $Rg_D \in H^1(\Omega)$ is the **lifting of** g_D , i.e., $Rg_D = g_D$ on $\partial\Omega$.



We recall that, for FEM- \mathbb{P}_1 , we have:

$$\mathcal{X}_h = \{v \in C^0(\bar{\Omega}) : v|_{T_k} \in \mathbb{P}_1, \forall T_k \in \mathcal{T}_h\}$$

while the Lagrangian basis is $\beta = \{\varphi_i\}_{i=1}^{N_h}$ (including the basis functions associated with the Dirichlet nodes). Set:

$$\mathcal{I} = \{1, 2, \dots, N_h\}, \quad \mathcal{I}_D = \{i \in \mathcal{I} : \mathbf{x}_i \in \partial\Omega_D\}, \quad \mathcal{I}_0 = \mathcal{I} \setminus \mathcal{I}_D.$$

The numerical solution is

$$u_h(x) = \sum_{j=1}^{N_h} u_j \varphi_j(x) = \underbrace{\sum_{j \in \mathcal{I}_0} u_j \varphi_j(x)}_{u_{0,h}} + \underbrace{\sum_{j \in \mathcal{I}_D} u_j \varphi_j(x)}_{Rg_{D,h}}$$

with **discrete lifting**

$$Rg_{D,h}(\mathbf{x}_i) = \begin{cases} g_D(\mathbf{x}_i) & \text{if } \mathbf{x}_i \in \partial\Omega_D \\ 0 & \text{otherwise.} \end{cases}$$



Set

- A matrix: $A_{ij} = a(\varphi_j, \varphi_i)$ with $i, j \in \mathcal{I}$,
- A_0 the block of A with $i, j \in \mathcal{I}_0$,
- A_D the block of A with $i \in \mathcal{I}_0$ e $j \in \mathcal{I}_D$,
- \mathbf{f} array: $f_i = F(\varphi_i)$ with $i \in \mathcal{I}$,
- \mathbf{f}_0 block of \mathbf{f} with $i \in \mathcal{I}_0$,
- \mathbf{g}_D block of $g_D(\mathbf{x}_i)$ with $i \in \mathcal{I}_D$,
- $\mathbf{u}_0 = [u_j]_{j \in \mathcal{I}_0}$, non-Dirichlet dof,
- $\mathbf{u}_D = [u_j]_{j \in \mathcal{I}_D}$, Dirichlet dof.

The algebraic formulation of the discrete Galerkin problem reads:

$$\begin{bmatrix} A_0 & A_D \\ 0 & I \end{bmatrix} \begin{bmatrix} \mathbf{u}_0 \\ \mathbf{u}_D \end{bmatrix} = \begin{bmatrix} \mathbf{f}_0 \\ \mathbf{g}_D \end{bmatrix} \quad \begin{array}{l} \leftarrow i \in \mathcal{I}_0 \text{ non-Dirichlet nodes} \\ \leftarrow i \in \mathcal{I}_D \text{ Dirichlet nodes} \end{array}$$



We have

$$\mathbf{u}_D = \mathbf{g}_D, \quad A_0 \mathbf{u}_0 + A_D \mathbf{u}_D = \mathbf{f}_0$$

and

$$A_0 \mathbf{u}_0 = \mathbf{f}_0 - A_D \mathbf{g}_D.$$

Finally, we reconstruct

$$\mathbf{u} = \begin{bmatrix} \mathbf{u}_0 \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} \mathbf{0} \\ \mathbf{u}_D \end{bmatrix}$$

- FEM.Kc contains the matrix A_0
- FEM.Fc contains the array $\mathbf{f}_0 - A_D \mathbf{g}_D$
- FEM.B contains the matrix B s.t. $B \mathbf{u}_0 = \begin{bmatrix} \mathbf{u}_0 \\ \mathbf{0} \end{bmatrix}$
- FEM.ud contains the array $\begin{bmatrix} \mathbf{0} \\ \mathbf{u}_D \end{bmatrix}$

To compute \mathbf{u} :

```
u0=FEM.Kc\FEM.Fc; % solve FEM.Kc u0 = FEM.Fc
u=FEM.B*u0+FEM.ud; % reconstruct u
```

